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## Introduction to Pattern Recognition

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## Human Perception

- Humans have developed highly sophisticated skills for sensing their environment and taking actions according to what they observe, e.g.,
  - Recognizing a face.
  - Understanding spoken words.
  - Reading handwriting.
  - Distinguishing fresh food from its smell.



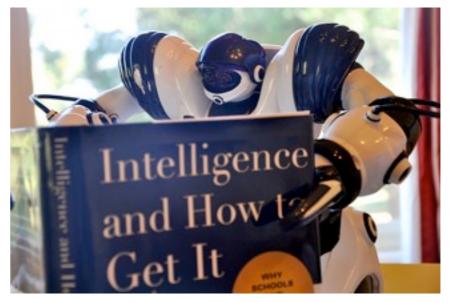


## Human and Machine Perception

- We are often influenced by the knowledge of how patterns are modeled and recognized in nature when we develop pattern recognition algorithms.
- Research on machine perception also helps us gain deeper understanding and appreciation for pattern recognition systems in nature.
- Yet, we also apply many techniques that are purely numerical and do not have any correspondence in natural systems.



- Pattern Recognition is the study of how machines can:
  - observe the environment,
  - learn to distinguish patterns of interest,
  - make sound and reasonable decisions about the categories of the patterns.



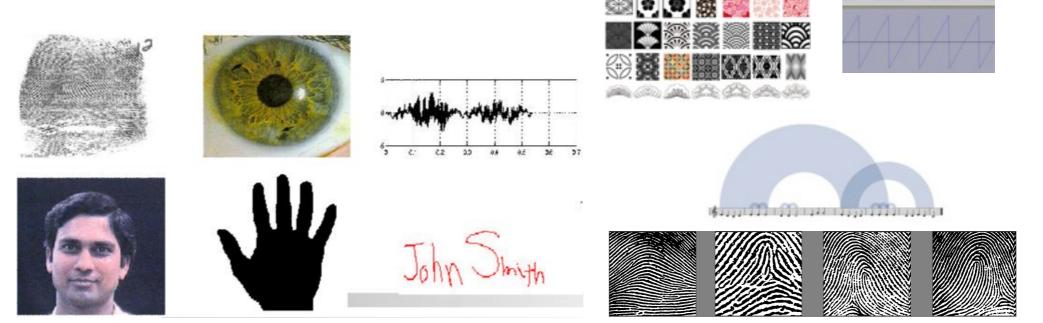


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### • What is a Pattern?

- is an abstraction, represented by a set of measurements describing a "physical" object
- Many types of patterns exist:

- visual, temporal, sonic, logical, ...

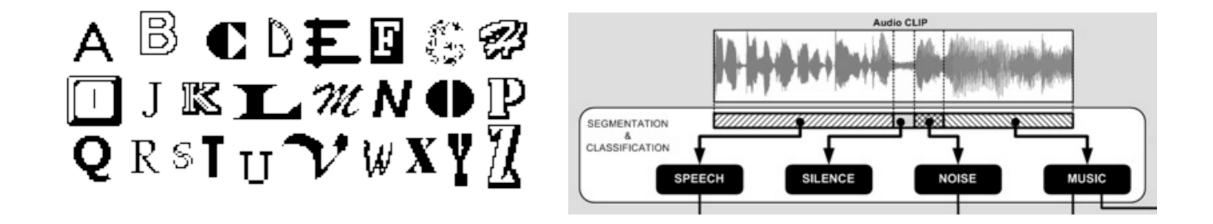




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### • What is a Pattern Class (or category)?

- is a set of patterns sharing common attributes
- a collection of "similar", not necessarily identical, objects
- During recognition, given objects are assigned to a prescribed class





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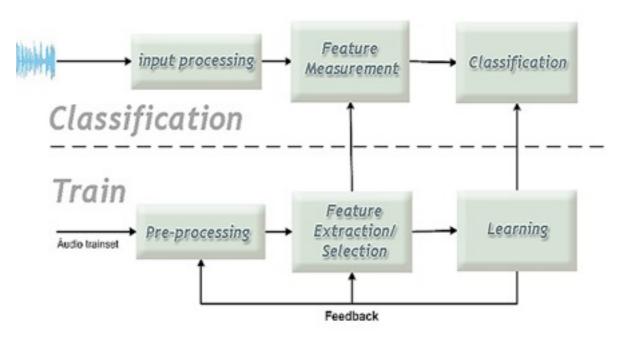
- No single theory of Pattern Recognition can possibly cope with such a broad range of problems...
- However, there are several standard models, including:
  - -<u>Statistical</u> or fuzzy pattern recognition (see <u>Fukunaga</u>)
  - Syntactic or structural pattern recognition (see Schalkoff)
  - Knowledge-based pattern recognition (see <u>Stefik</u>)



### • Two phase Process

### I.Training/Learning

- Learning is hard and time consuming
- System must be exposed to several examples of each class
- Creates a "model" for each class
- Once learned, it becomes natural
- 2.Detecting/Classifying





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- How can a machine learn the rule from data?
  - -Supervised learning: a teacher provides a category label or cost for each pattern in the training set.

➡Classification

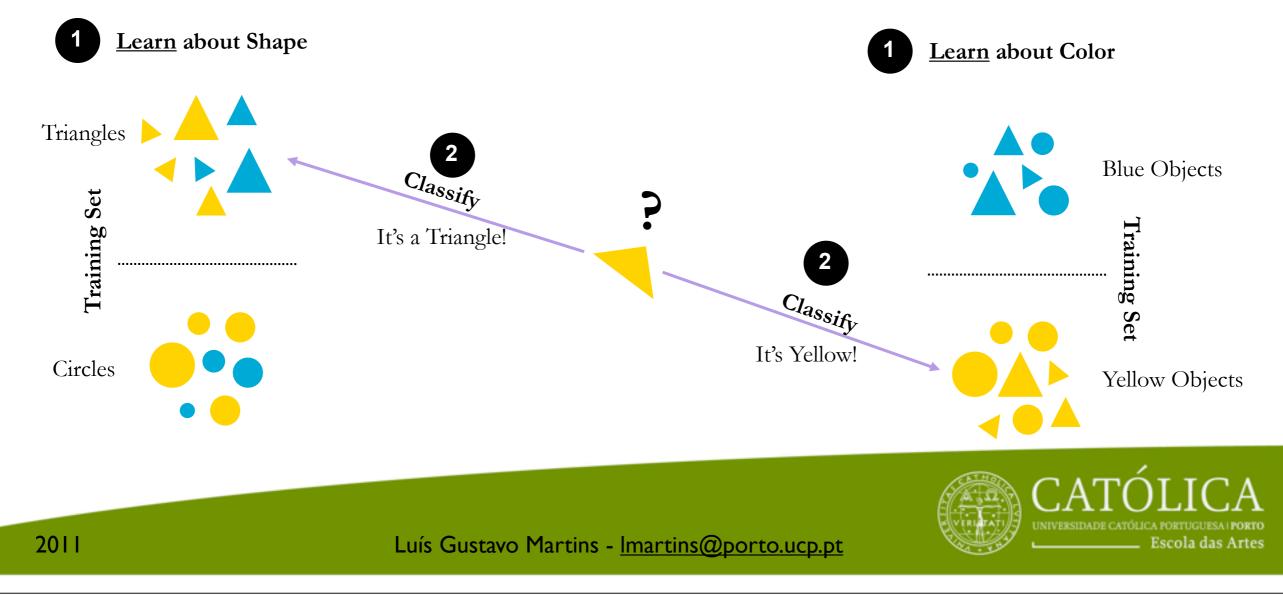
- Unsupervised learning: the system forms clusters or natural groupings of the input patterns (based on some similarity criteria).

➡Clustering

• **Reinforcement learning:** no desired category is given but the teacher provides feedback to the system such as the decision is right or wrong.

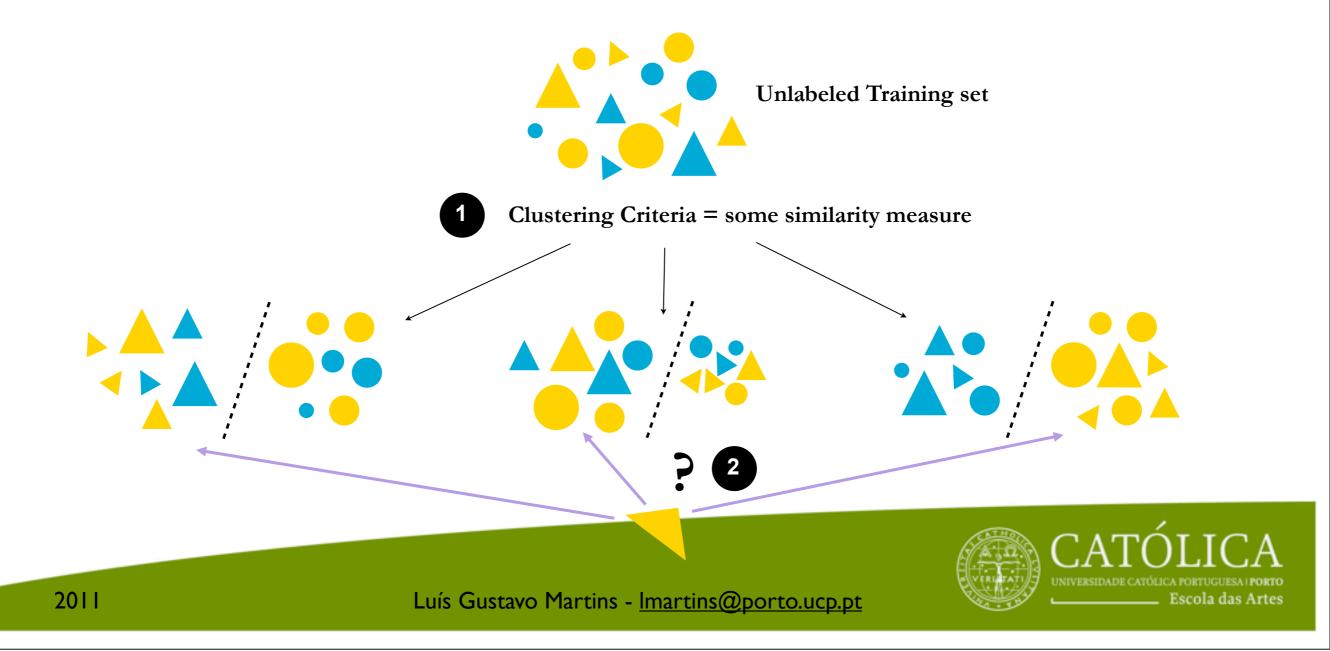
### Supervised Training/Learning

- a "teacher" provides labeled training sets, used to train a classifier



### Unsupervised Training/Learning

- No labeled training sets are provided
- System applies a specified clustering/grouping criteria to unlabeled dataset
- Clusters/groups together "most similar" objects (according to given criteria)



## Pattern Recognition Process

### • Data acquisition and sensing:

- Measurements of physical variables.
- Important issues: bandwidth, resolution , etc.

### • Pre-processing:

- Removal of noise in data.
- Isolation of patterns of interest from the background.

### • Feature extraction:

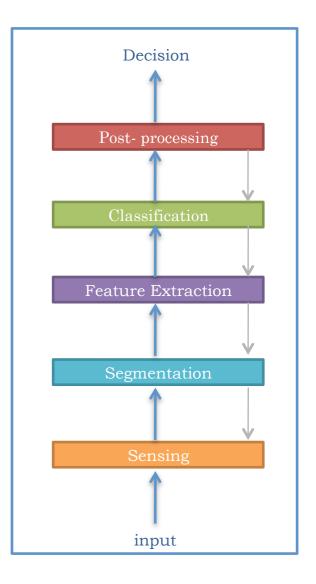
- Finding a new representation in terms of features.

### • Classification

Using features and learned models to assign a pattern to a category.

### Post-processing

- Evaluation of confidence in decisions.





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### Features

- Features are properties of an object:
  - Ideally representative of a specific type (i.e. class) of objects
  - Compact (memory efficient)
  - Computationally simple (CPU efficient)
  - Perceptual relevant (if trying to implement a human inspired classifier)
- => Should pave the way to a good discrimination of different classes of objects!

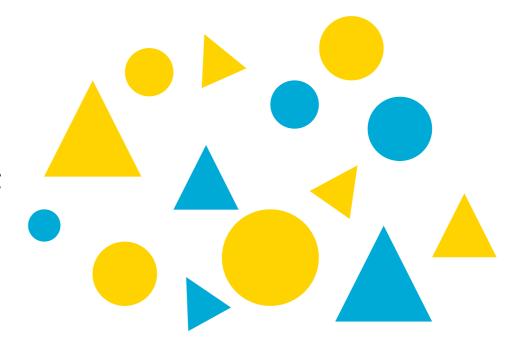


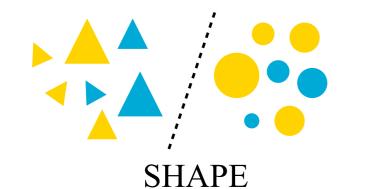
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### Features

- Take a group of graphical objects
  - Possible features:
    Shape
    Color
    Size

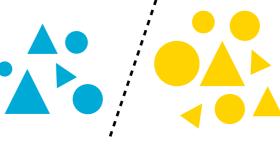
    - •
  - Allows to group them into different classes:











COLOR



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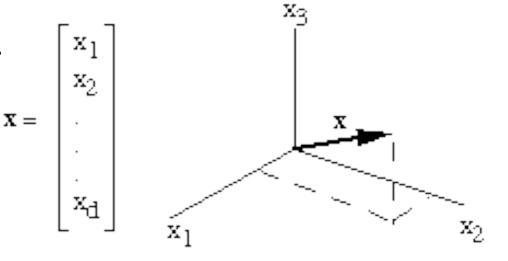
### **Feature Vectors**

- Usually a single object can be represented using several features, e.g.
  - $-\mathbf{x}\mathbf{I}$  = shape (e.g. nr of sides)
  - $\mathbf{x2} = \text{size (e.g. some numeric value)}$  $\mathbf{x3} = \text{color (e.g. rgb values)}$

  - **xd** = some other (numeric) feature.
- X becomes a feature vector

- x is a point in a d-dimensional **feature space**.







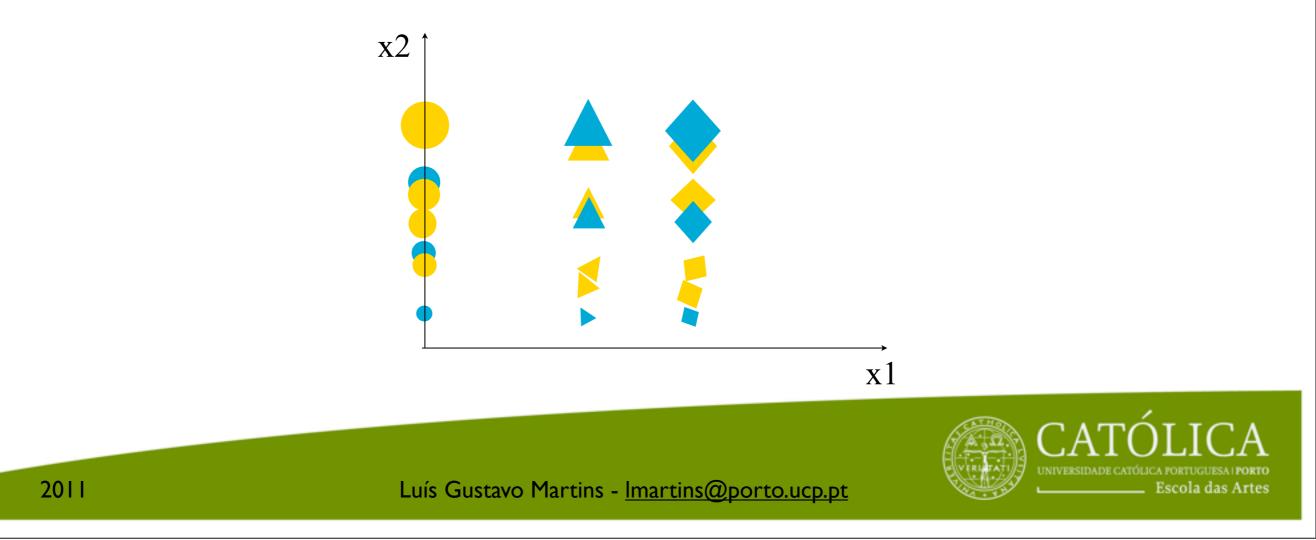
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### **Feature Vectors**

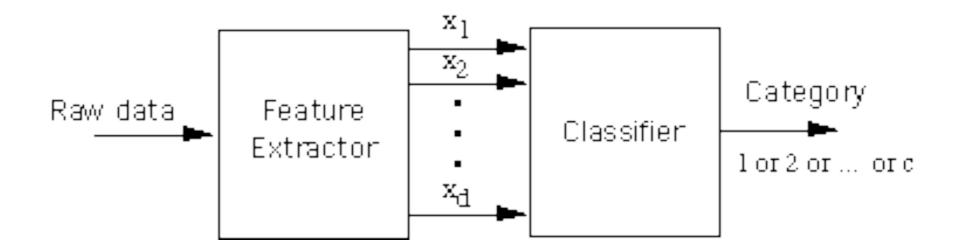
### • Example of a 2D Feature Space

- xI = shape (e.g. nr of sides)
  x2 = size (e.g. some numeric value)



### The Classical Model for PR

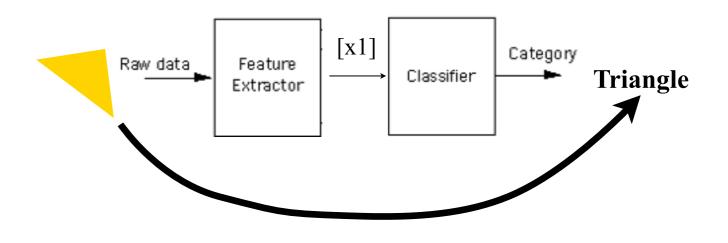
- I. A Feature Extractor extracts features from raw data (e.g. audio, image, weather data, etc)
- A Classifier receives X and assigns it to one of c categories, Class I, Class
   2, ..., Class c (i.e. labels the raw data).





## The Classical Model for PR

- Example: classify graphic objects according to their shape
  - Feature extracted:
    - nr. of sides (x1)
  - Classifier:
    - 0 sides => circle
    - 3 sides => triangle
    - (4 sides => rectangle)



 How does the classifier know that a circle has no sides and that a triangle has 3 sides?!



### • Problem:

- -sort incoming fish on a conveyor belt according to species
- -Assume only two classes exist:
  - Sea Bass and Salmon

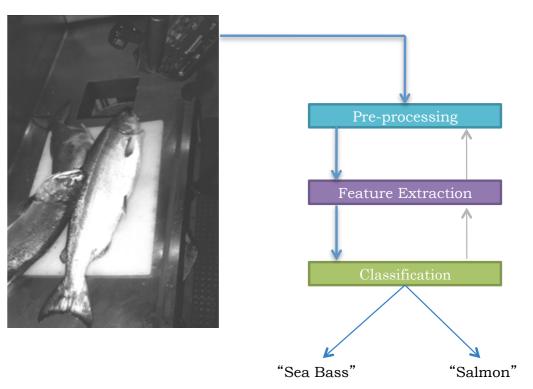






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- What kind of information can distinguish one species from the other?
- length, width, weight, number and shape of fins, tail shape, etc.
- What can cause problems during sensing?
- lighting conditions, position of fish on the conveyor belt, camera noise, etc.
- What are the steps in the process?
  - I.Capture image.
  - 2.Isolate fish
  - 3. Take measurements
  - 4. Make decision

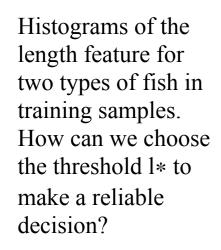


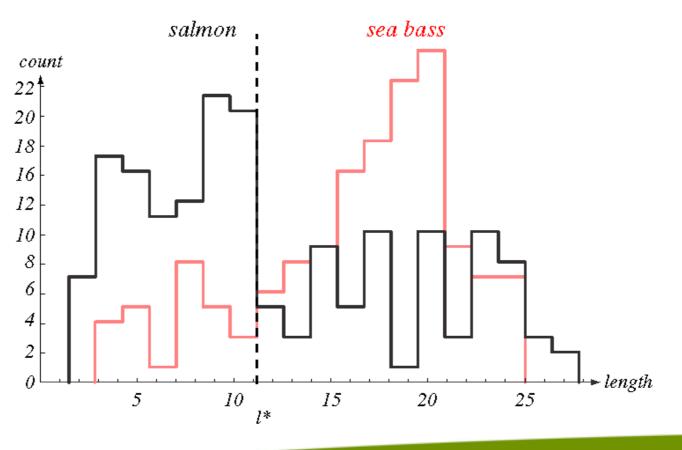


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### • Selecting Features

- Assume a fisherman told us that a sea bass is generally longer than a salmon.
- We can use <u>length as a feature</u> and decide between sea bass and salmon according to a threshold on length.
- How can we choose this threshold?





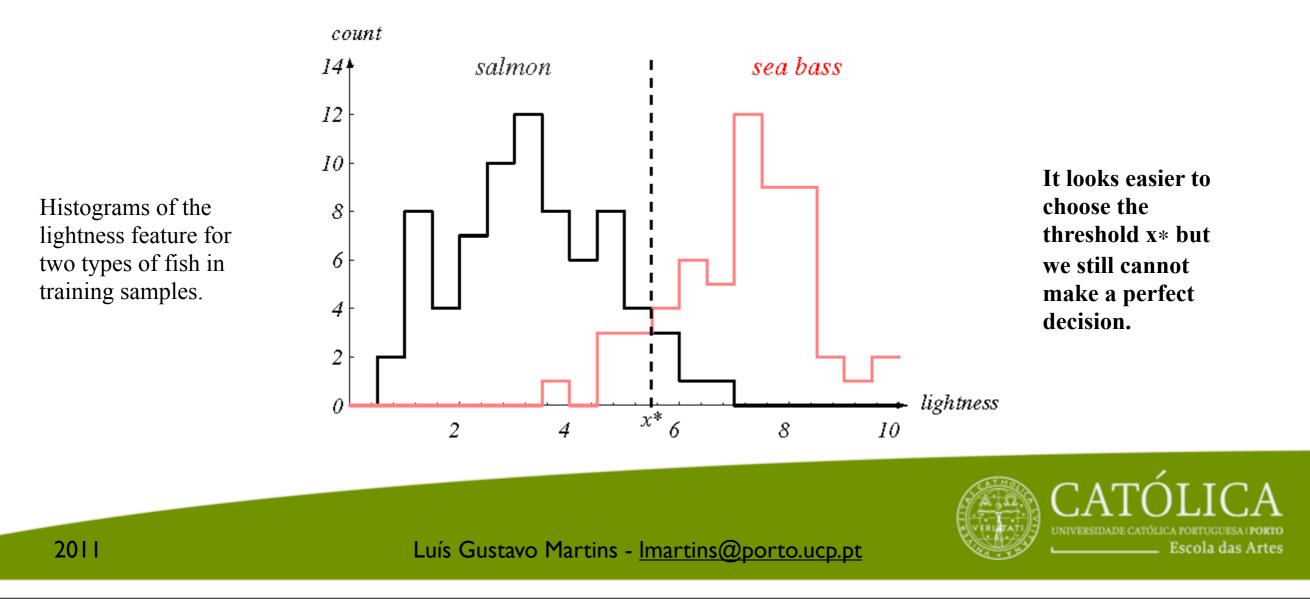
Even though "sea bass" is longer than "salmon" on the average, there are many examples of fish where this observation does not hold...



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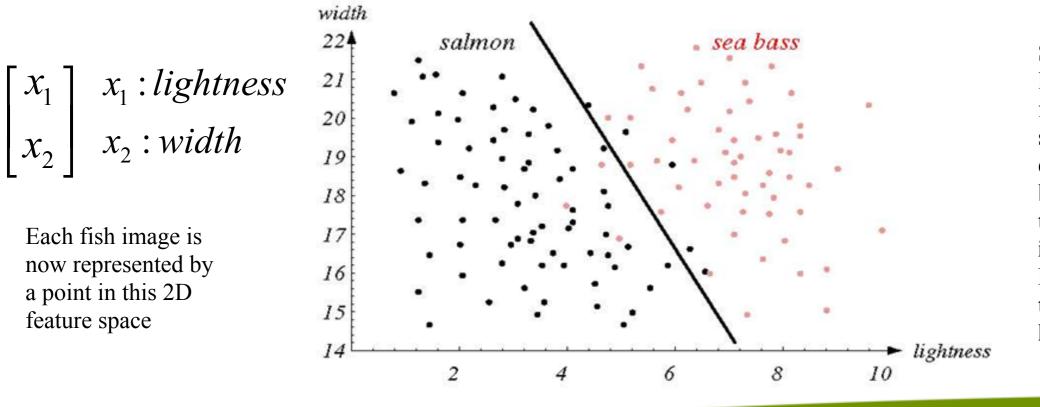
### Selecting Features

- Let's try another feature and see if we get better discrimination
  - →Average Lightness of the fish scales



### • Multiple Features

- Single features might not yield the best performance.
- To improve recognition, we might have to use more than one feature at a time.
- Combinations of features might yield better performance.
- Assume we also observed that sea bass are typically wider than salmon.



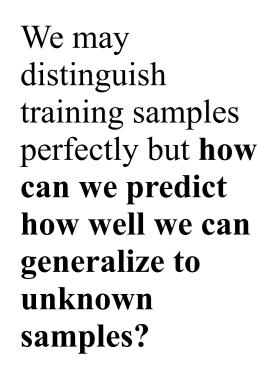
Scatter plot of lightness and width features for training samples. We can draw a decision boundary to divide the feature space into two regions. Does it look better than using only lightness?

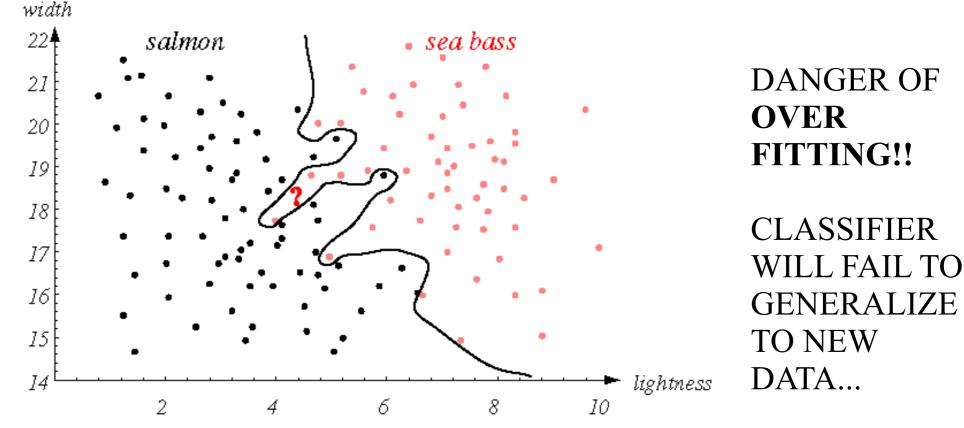


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- Designing a Classifier
  - Can we do better with another decision rule?
  - More complex models result in more complex boundaries.



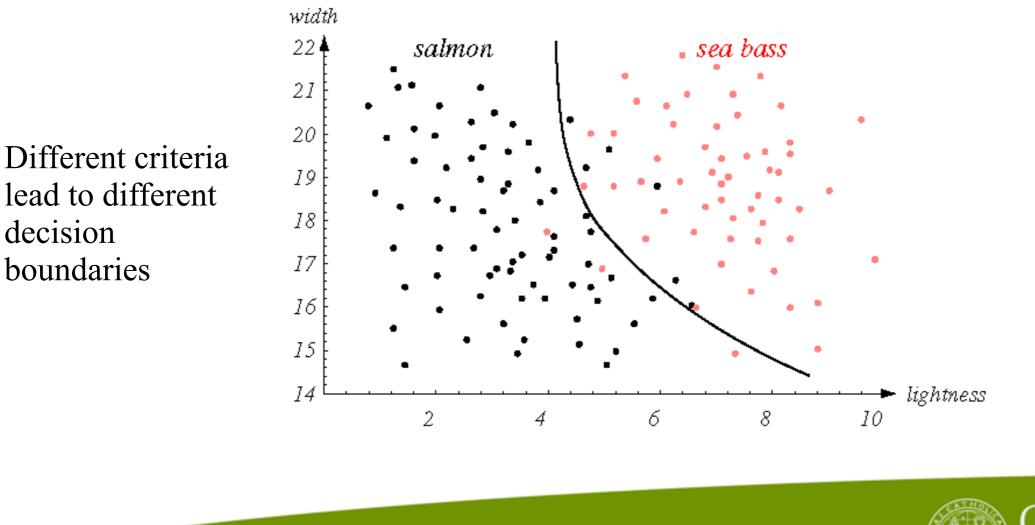




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### Designing a Classifier

• How can we manage the tradeoff between complexity of decision rules and their performance to unknown samples?





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- Designing a Feature Extractor
  - Its design is **problem specific** (e.g. features to extract from graphic objects may be quite different from sound events...)
  - The ideal feature extractor would produce the same feature vector X for all patterns in the same class, and different feature vectors for patterns in different classes.
  - In practice, different inputs to the feature extractor will always produce different feature vectors, but we hope that the **within-class variability** is small relative to the **between-class variability**.
- Designing a good set of features is sometimes "more of an art than a science"...



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### • Multiple Features

- Does adding more features always improve the results?

### • No!! So we must:

- Avoid unreliable features.
- Be careful about correlations with existing features.
- Be careful about measurement costs.
- Be careful about noise in the measurements.

### - Is there some curse for working in very high dimensions?

• YES THERE IS! ==> CURSE OF DIMENSIONALITY

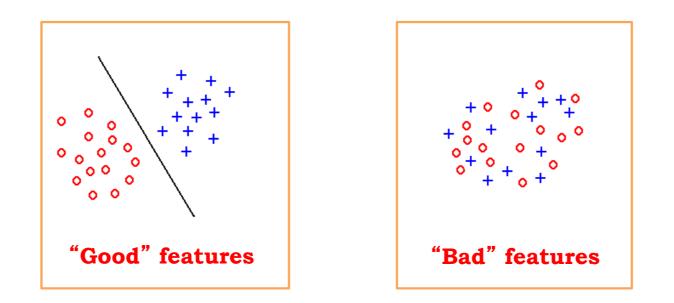
 $\Rightarrow thumb rule: n \ge d(d-1)/2 \quad n = nr of examples in training dataset$ d = nr of features



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### • Problem: Inadequate Features

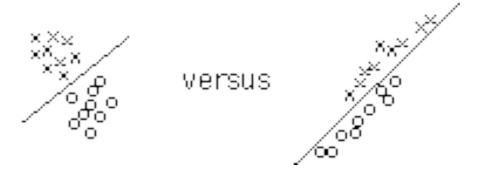
- features simply do not contain the information needed to separate the classes, it doesn't matter how much effort you put into designing the classifier.
- -Solution: go back and design better features.





### • Problem: Correlated Features

- Often happens that two features that were meant to measure different characteristics are influenced by some common mechanism and tend to vary together.
  - E.g. the perimeter and the maximum width of a figure will both vary with scale; larger figures will have both larger perimeters and larger maximum widths.
- This degrades the performance of a classifier based on Euclidean distance to a template.
  - A pattern at the extreme of one class can be closer to the template for another class than to its own template. A similar problem occurs if features are badly scaled, for example, by measuring one feature in microns and another in kilometers.
- Solution: (Use other metrics, e.g. Mahalanobis...) or extract features known to be uncorrelated!





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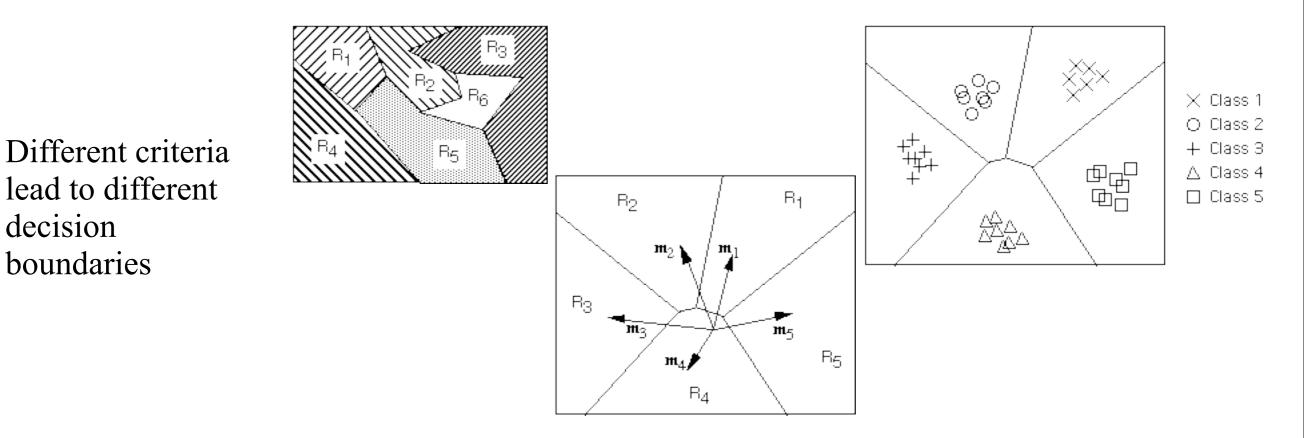
- Model selection:
  - Domain dependence and prior information.
  - Definition of design criteria.
  - Parametric vs. non-parametric models.
  - Handling of missing features.
  - Computational complexity.
  - Types of models: templates, decision-theoretic or statistical, syntactic or structural, neural, and hybrid.
  - How can we know how close we are to the true model underlying the patterns?



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### • Designing a **Classifier**

• How can we manage the tradeoff between complexity of decision rules and their performance to unknown samples?





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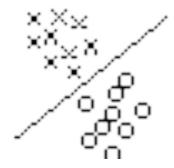
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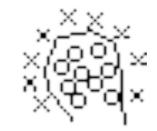
decision

### • Problem: Curved Boundaries

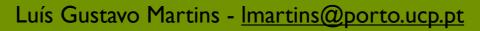
- linear boundaries produced by a minimum-Euclidean-distance classifier may not be flexible enough.
  - For example, if x1 is the perimeter and x2 is the area of a figure, x1 will grow linearly with scale, while x2 will grow quadratically. This will "warp" the feature space and prevent a linear discriminant function from performing well.
- Solutions:
  - Redesign the feature set (e.g., let x2 be the square root of the area)
  - Try using <u>Mahalanobis distance</u>, which can produce quadratic decision boundaries
  - Try using a neural network (beyond the scope of these notes; see <u>Haykin</u>)



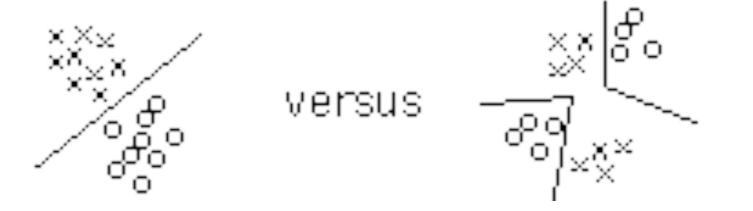
versus





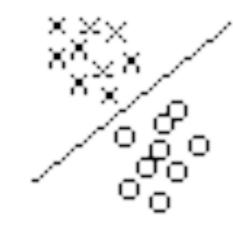


- Problem: Subclasses in the dataset
  - frequently happens that the classes defined by the end user are not the "natural" classes...
  - Solution: use CLUSTERING.

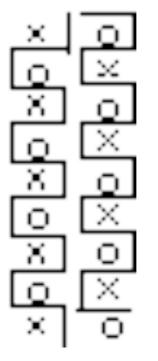




- Problem: Complex Feature Space
  - Solution: use different type of Classifier...



versus

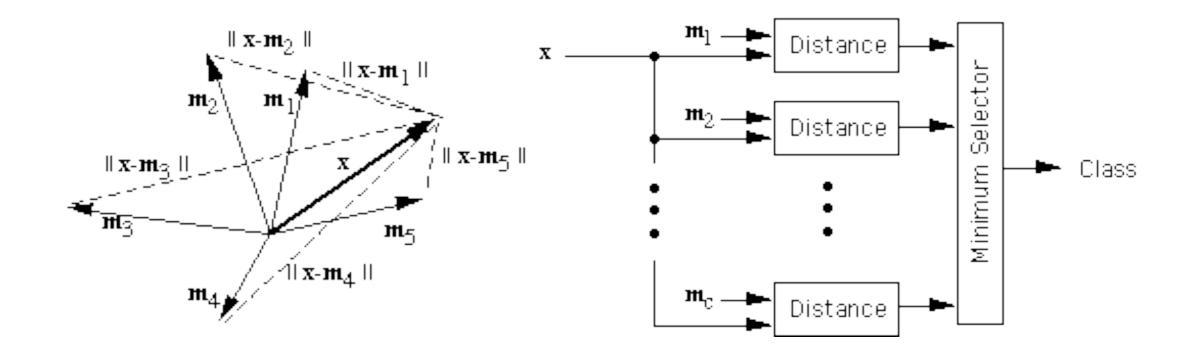




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## Simple Classifiers

- Minimum-distance Classifiers
  - based on some specified "metric" ||x-m||
  - e.g. Template Matching

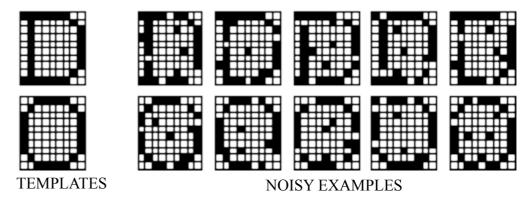




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## Simple Classifiers

• Template Matching



- To classify one of the noisy examples, simply compare it to the two templates. This can be done in a couple of equivalent ways:
  - I. Count the number of agreements. Pick the class that has the maximum number of agreements. This is a maximum correlation approach.
  - 2. Count the number of disagreements. Pick the class with the minimum number of disagreements. **This is a minimum error approach.**
- Works well when the variations within a class are due to "additive noise", and there are no other distortions of the characters -- translation, rotation, shearing, warping, expansion, contraction or occlusion.



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## Simple Classifiers

### Metrics

- different ways of measuring distance:

#### • Euclidean metric:

- || u || = sqrt( u | 2 + u 22 + ... + u d2 )
- Manhattan (or taxicab) metric:

- || u || = |u| + |u| + |u|

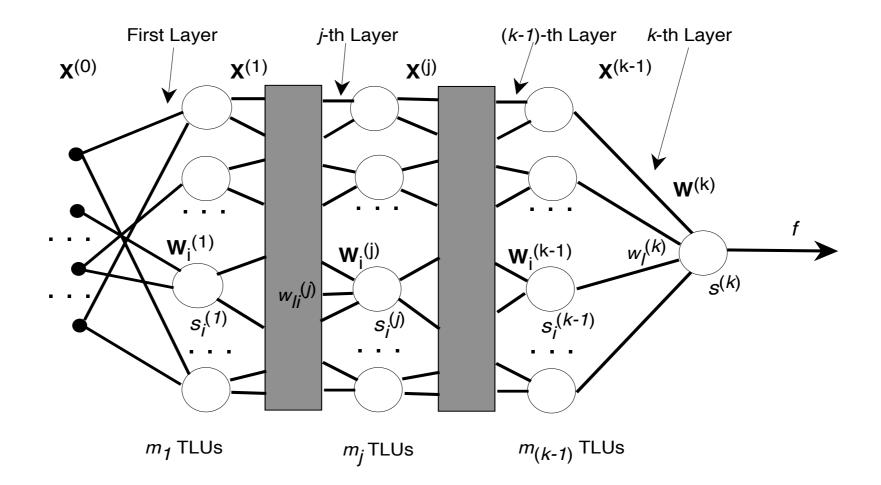
- Contours of constant...
  - ... Euclidean distance are circles (or spheres)
  - ... Manhattan distance are squares (or boxes)
  - ... Mahalanobis distance are ellipses (or ellipsoids)





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### Classifiers: Neural Networks



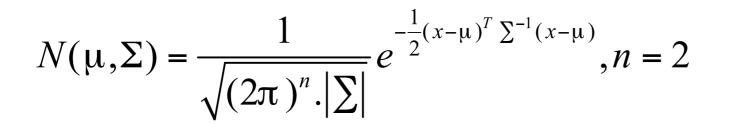
http://robotics.stanford.edu/people/nilsson/MLBOOK.pdf

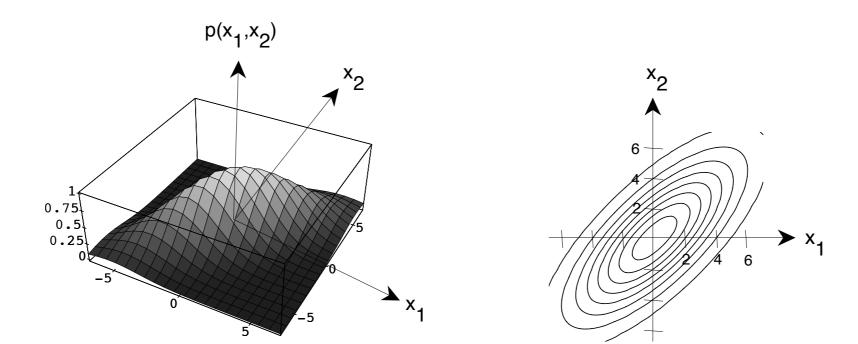


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### Gaussian Modeling





http://robotics.stanford.edu/people/nilsson/MLBOOK.pdf

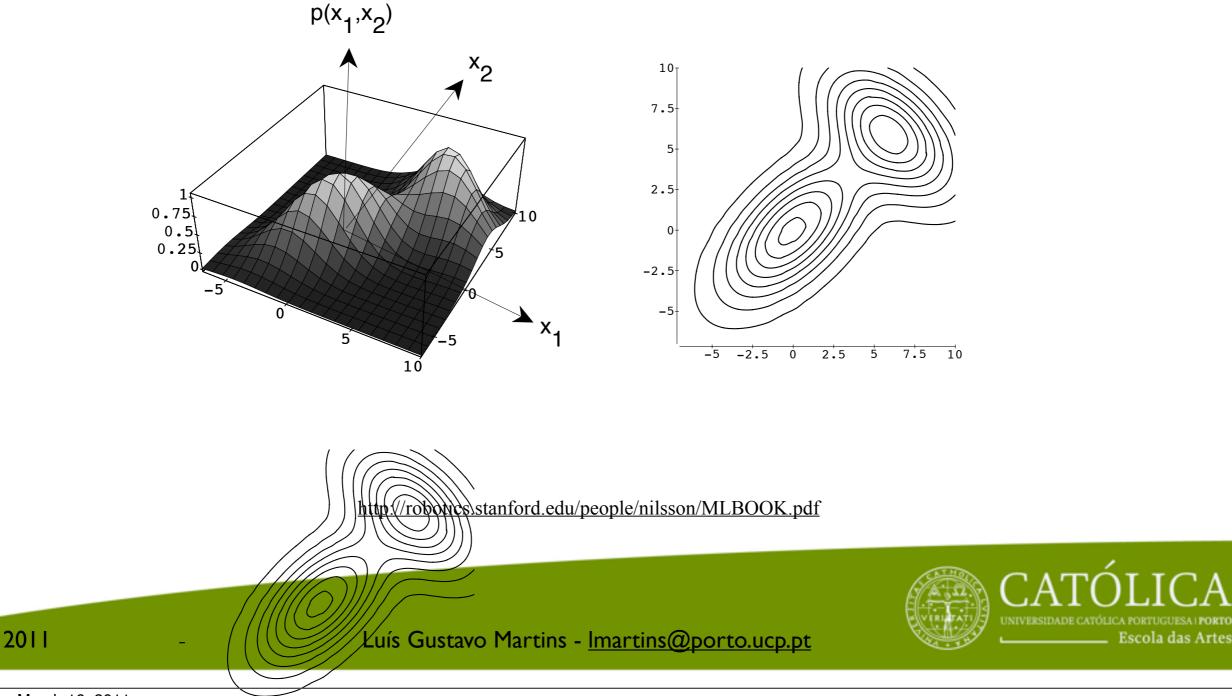


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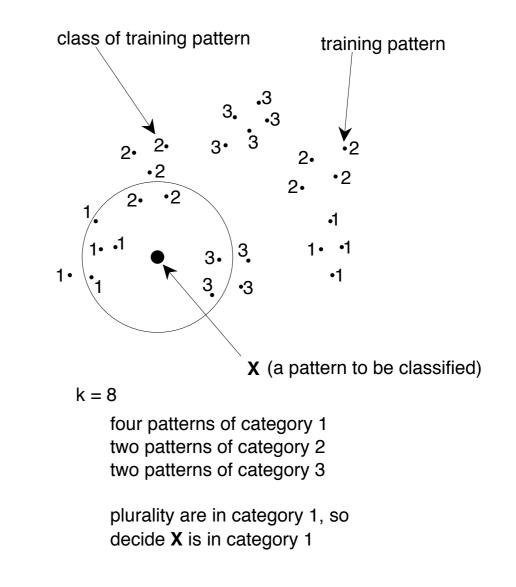
### Gaussian Mixture Models

• Use multiple Gaussians to model the data



### Classifiers: kNN

- k-Nearest Neighbours
   Classifier
  - -Lazy Classifier
    - no training is actually performed (hence, lazy ;-))
  - An example of Instance Based Learning



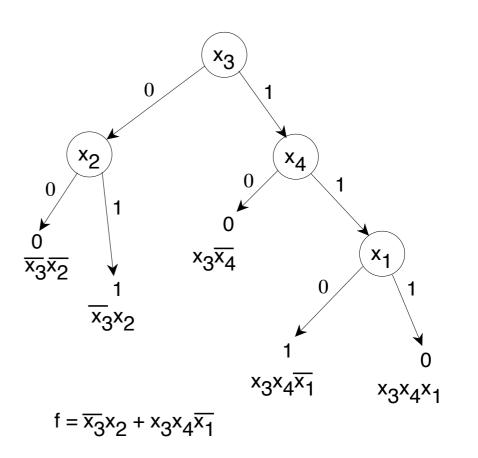
http://robotics.stanford.edu/people/nilsson/MLBOOK.pdf



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### **Decision Trees**

- Learn rules from data
- Apply each rule at each node
- classification is at the leafs of the tree

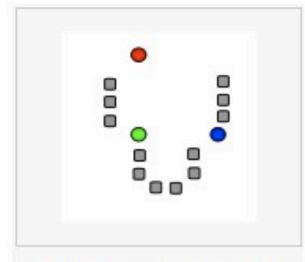


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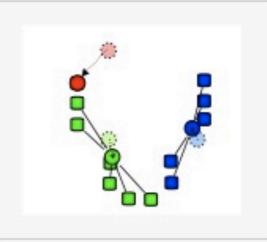
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### Clustering: k-means

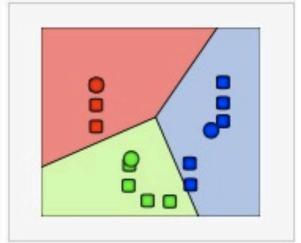


 k initial "means" (in this case k=3) are randomly selected from the data set (shown in color).

 k clusters are created by associating every observation with the nearest mean. The partitions here represent the Voronoi diagram generated by the means.



 The centroid of each of the k clusters becomes the new means.



 Steps 2 and 3 are repeated until convergence has been reached.

http://en.wikipedia.org/wiki/K-means\_clustering



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### Evaluating a Classifier

#### • Training Set

- used for training the classifier

#### • Testing Set

- examples not used for training
- avoids overfitting to the data
- tests generalization abilities of the trained classifiers
- Data sets are usually hard to obtain...
  - Labeling examples is time and effort consuming
  - Large labeled datasets usually not widely available
  - Requirement of separate training and testing datasets imposes higher difficulties...
  - -Use **Cross-Validation** techniques!

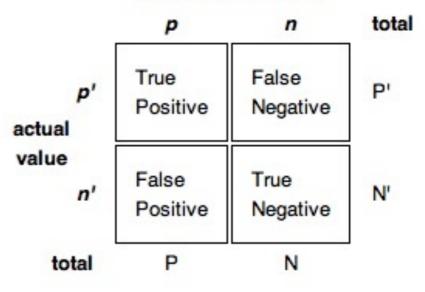


### Evaluating a Classifier

### • Confusion Matrix

Exa	mple co	Predicted		
				Rabbit
Actual	Cat	5	3	0
	Dog	2	3	1
	Rabbit	0	2	11

#### prediction outcome



http://en.wikipedia.org/wiki/Confusion\_matrix



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### Evaluating a Classifier

### • Costs of Error

- -We should also consider costs of different errors we make in our decisions. For example, if the fish packing company knows that:
  - Customers who buy salmon will object vigorously if they see sea bass in their cans.
  - Customers who buy sea bass will not be unhappy if they occasionally see some expensive salmon in their cans.
- How does this knowledge affect our decision?



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# Pattern Recognition References

- Introduction to Machine Learning Draft of Incomplete Notes, by <u>Nils J. Nilsson</u> (http:// robotics.stanford.edu/people/nilsson/MLBOOK.pdf)
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- PR for HCI Richard O. Duda notes (<u>http://www.cs.princeton.edu/courses/archive/fall08/</u> <u>cos436/Duda/PR\_home.htm</u>)
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# Pattern Recognition References

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- WEKA Data Mining Software in Java (<u>http://www.cs.waikato.ac.nz/ml/weka/</u>)



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